### Acting Irrationally to Improve Performance in **Stochastic Worlds**

Roman V. Belavkin (r.belavkin@mdx.ac.uk)

School of Computing Science, Middlesex University, London NW4 4BT, UK

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### **OVERVIEW**

- 1. Motivation of this work
- 2. Critique of the rational d.m. theory
- 3. Irrational decision-making
- 4. The architecture
- 5. Experimental results
- 6. Discussion

### MOTIVATION

- Humans and animals always express some degree of Suydam, 1963) randomness in their choice behaviour (Myers, Fort, Katz, &
- Cognitive architectures add noise into utility to model the 'irrational' component (e.g. ACT-R, Anderson & Lebiere, 1998)
- Noise seems to play an important role optimising the behaviour (Belavkin & Ritter, 2003)
- The expected utility theory leads to many unexplained paradoxes.

### **EXPECTED UTILITY THEORY**

- The classical decision-making theory is due to Bernoulli (1954) and Anscombe and Aumann (1963). (1738/1954), von Neumann and Morgenstern (1944), Savage
- The central idea is to represent preferences by some utility function  $u:X\to\mathbb{R}$

$$x \succ y \iff u(x) > u(y)$$

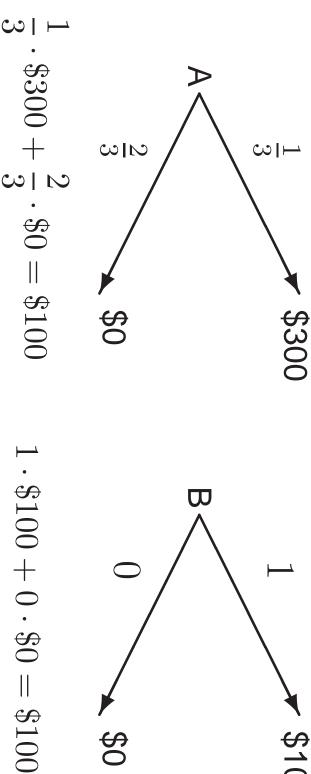
Under uncertainty, the expected utilities (EUs) are considered

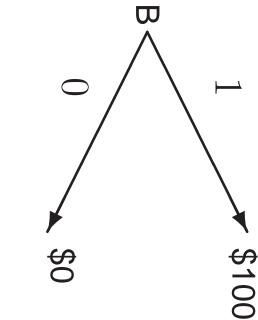
$$p \succ q \iff \sum_{z \in Z} p(z) \, u(z) > \sum_{z \in Z} q(z) \, u(z) \,,$$

where Z is a set of prizes, P a set of probability measures.

### THE ALLAIS PARADOX

in many interpretations. Consider two lotteries  ${\cal A}$  and  ${\cal B}$ Due to Allais (1953). Also studied by Tversky and Kahneman (1974)





About 80% of subjects express preference  $A \prec B$ .

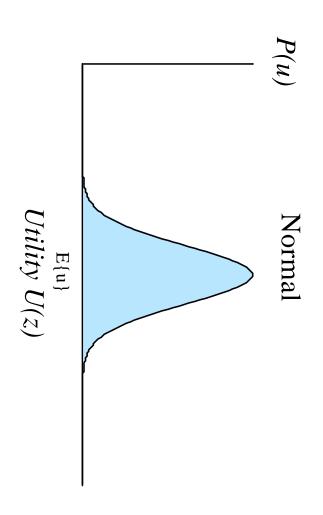
Professional traders behave this way too (List & Haigh, 2005).

### THE MAX EU PRINCIPLE

Many paradoxes occur when we try to apply

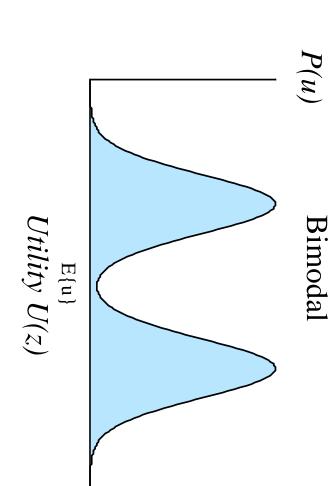
$$x = \arg\max_{x \in X} \sum_{z \in Z} p(z \mid x) u(z)$$

For Gaussian distributions,  $E\{u\}$  corresponds to  $\max P(u)$ 



# **NON-GAUSSIAN DISTRIBUTIONS**

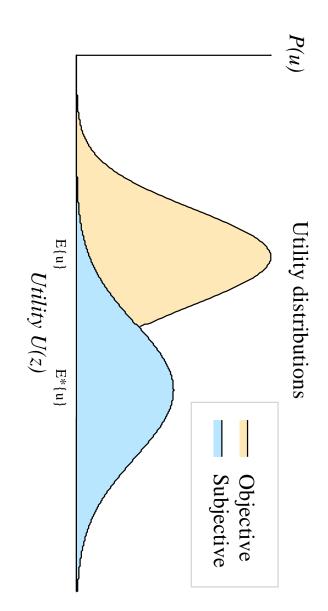
• In general,  $E\{u\} \neq \arg \max P(u)$ 



Often,  $E\{x\} \notin X$ , such as  $\$100 \notin \$0,\$300$ 

# **EXPLORATION VS EXPLOITATION**

Distributions  $P^{st}$  an agent uses may be only approximations of the objective probabilities P, and  $E^*\{u\} \neq E\{u\}$ .



- Is  $\max E\{u\}$  a good sampling strategy?
- Distributions  $P(\boldsymbol{z})$  may depend on the agent's actions.

## RANDOM DECISION-MAKING

Instead of  $\sum_{z} p(z \mid x) u(z)$ , we can use  $p(z \mid x)$  to draw zrandom utility u(z), and it can be used to choose xrandomly (i.e. Monte-Carlo). The utility of this outcome is called

$$x = \arg\max_{x \in X} u(z)$$
 , where  $z \leftarrow p(z \mid x)$ 

Sampling can be implemented using the inverse PDF method

Outcome 
$$= F^{-1}(p)$$
, where  $p \in (0,1)$ 

On average,  $z = rg \max p(z)$ 

## THE AGENT ARCHITECTURE

The following decision-theoretic agents architecture is used

$$X=\{x_1,\dots,x_m\}$$
 percepts  $Y=\{y_1,\dots,y_n\}$  preferences (e.g.  $Y=\{$ success, failure $\}$ )

 $=\{z_1,\ldots,z_k\}$ actions

- Transitions  $(x_i, y_j, z_k)$  are recorded in  $M_{ij}^k$
- Normalised  $M^k_{ij}$  is used as a Markov transition model  $P(X,Y,Z)=(p_{ij}^k)$ , where  $p_{ij}^k=p(x_i,y_j,z_k)$ .
- We can use Bayesian inference

$$P(Y\mid X,Z) = \alpha P(X,Y,Z) \,, \quad \text{where } \alpha = \tfrac{1}{\|P(Y\mid X,Z)\|}$$

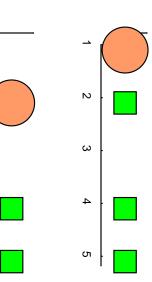
### LEARNING

- The memory is initialised to  $M^k_{ij}=I=(1).$  Normalised, it  $\max H(X,Y,Z) = \ln(m \times n \times k)$  (i.e. no information). represents uniform distribution that yields maximum entropy
- The preference relations influence the action selection mechanism, which makes X, Y and Z statistically dependent
- Mutual information can measure this dependence

$$I(X, Y, Z) = H(X) + H(Y) + H(Z) - H(X, Y, Z)$$

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### THE EXPERIMENT



Percepts:

 $X = \{x_1, \dots, x_5\}$ 

Preferences:

 $Y = \{$ success, failure $\}$ 

Actions:

 $Z = \{ \text{left, stay, right} \}$ 

and at different rates. The rewards appear randomly according to some distribution law

The performance of agents can be measured and compared by the number of rewards they manage to collect.

### **ACTION SELECTION**

Three agents were used in tests. The only difference was how actions

were selected from  ${\cal Z}$ 

#### max EU

$$z = \arg\max_{z \in Z} \sum_{y \in Y} p(y \mid x, z) u(y)$$

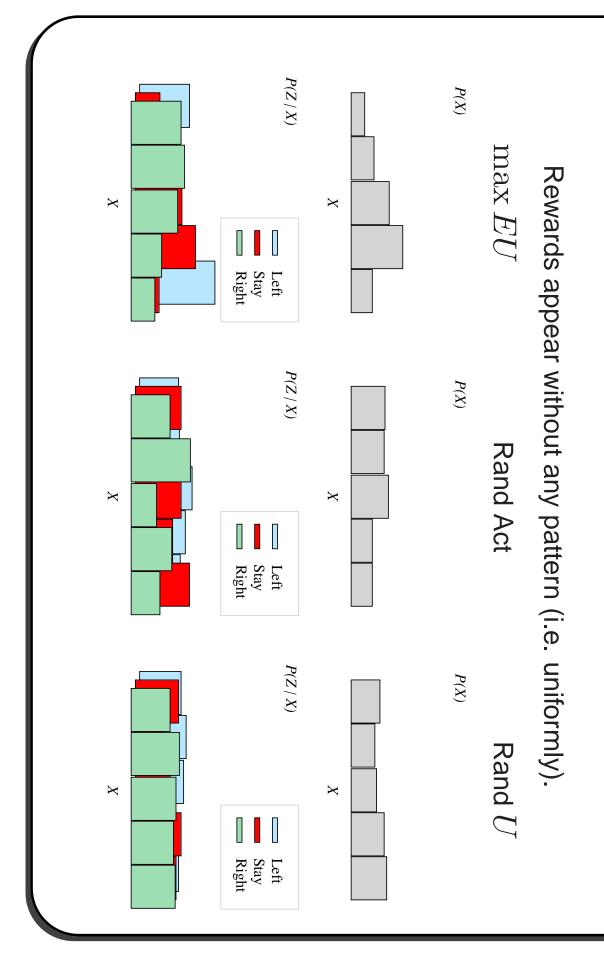
#### rand Act

$$z \leftarrow p(z \mid x, \arg\max_{y \in Y} u(y))$$

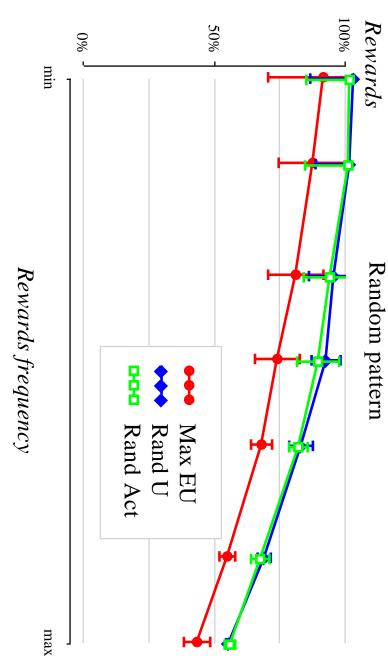
#### rand U

$$z = \arg\max_{z \in Z} u(y) \,, \quad \text{where } y \leftarrow p(y \mid x, z)$$

## **COMPLETELY RANDOM WORLD**

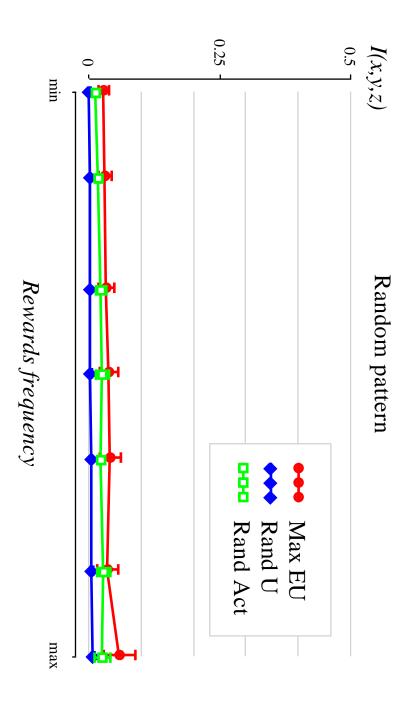




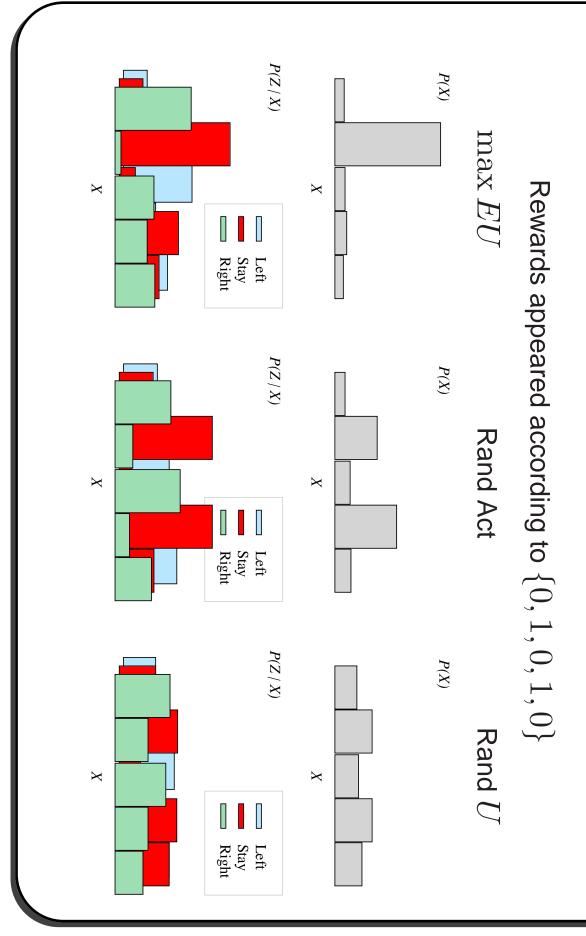


The random agents are not doing too bad!

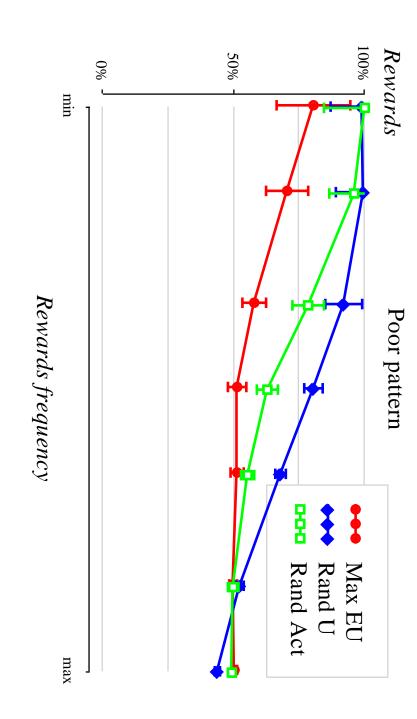
# **MUTUAL INFORMATION (NO PATTERN)**



## **REGULAR PATTERN (POOR)**

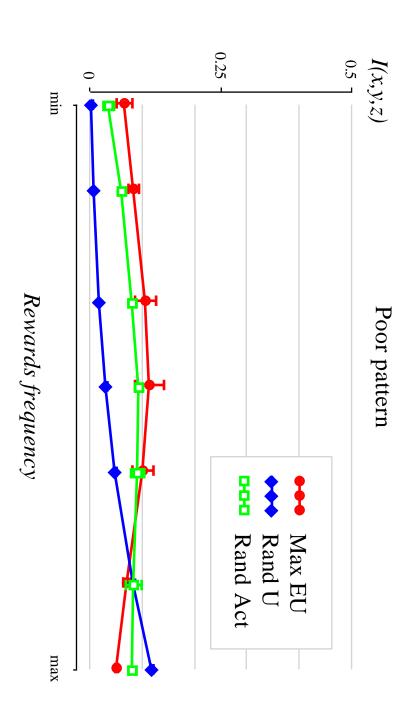


## PERFORMANCE (REGULAR 1)



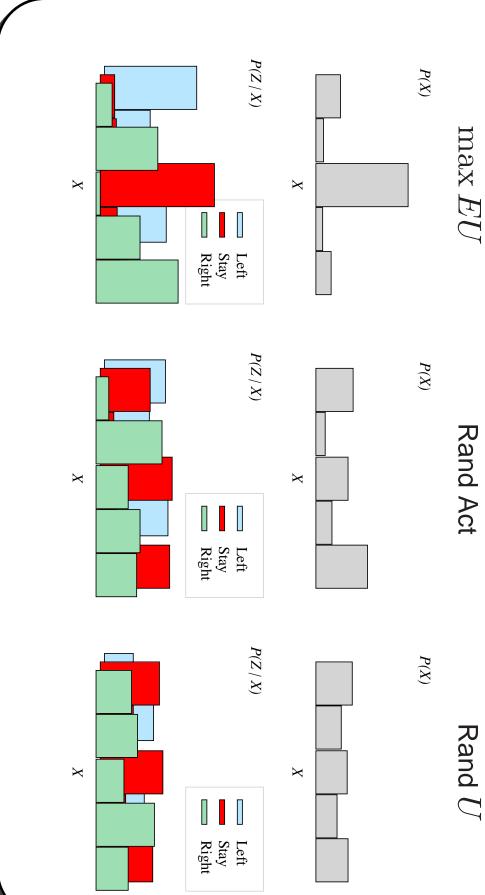
The random agents outperform  $\max EU$  almost 2:1.





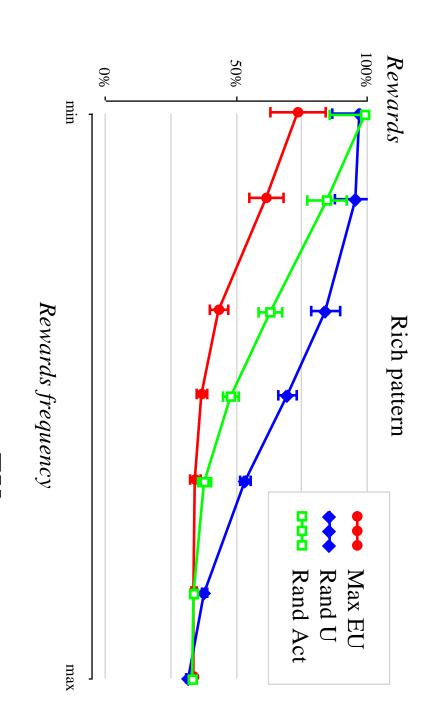
### **REGULAR PATTERN (RICH)**

Rewards appeared according to  $\{1,0,1,0,1\}$ 



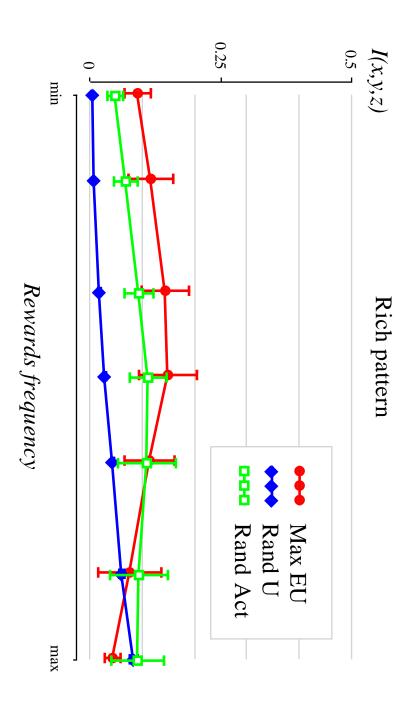
 $\operatorname{Rand} U$ 

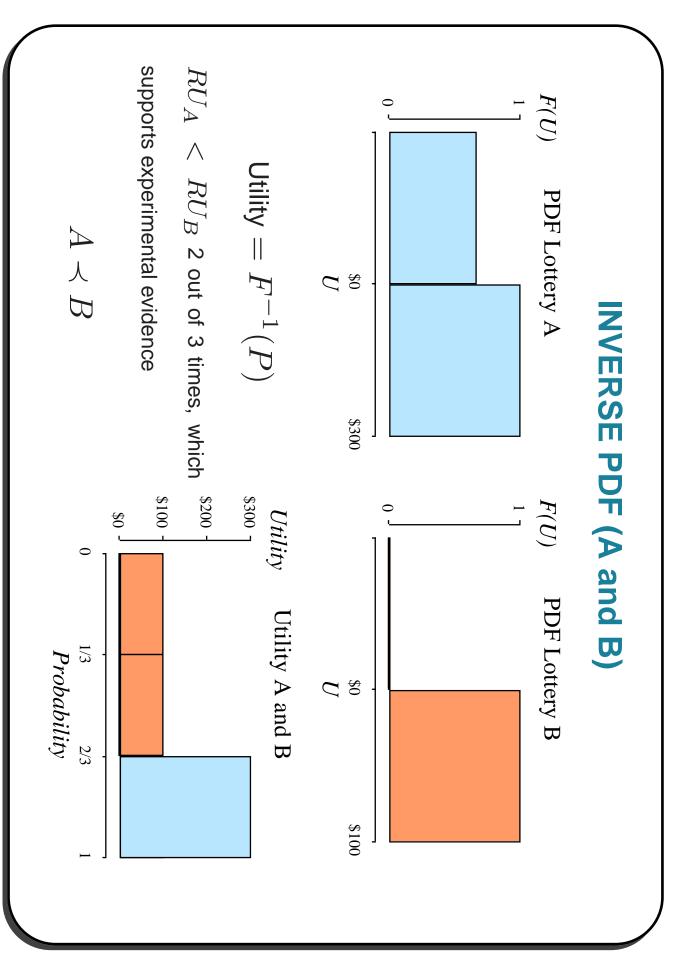
## PERFORMANCE (REGULAR 2)



Again, random outperform  $\max EU$  as much as 2:1.

# **MUTUAL INFORMATION (REGULAR 2)**





- Here, the  $\max EU$  method turned to be inferior to the Monte-Carlo methods
- The random agents not only maximise the utility, but also sample the distributions (exploration vs exploitation).
- Monte–Carlo methods use all statistics (not just E).
- Random d.m. accommodates better human choice behaviour.
- The inverse PDF provides some clues for the Allais paradox.
- Should we go back to the game theory? (e.g. the Prisoners' dilemma)

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