

# Lecture 6: Stochastic differential equations and integrals

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## 1 Stochastic differential equations

### Stochastic differential equations

**Definition 1** (Stochastic differential equations). Equations of the form

$$dx(t) = f(x, t) dt + g(x, t) dw(t)$$

where  $w(t)$  is the Wiener process, and  $f(x, t)$ ,  $g(x, t)$  are some functions.

- Compare an SDE to an ordinary differential equation:

$$\frac{dx(t)}{dt} = f(x, t) \quad \text{or} \quad dx(t) = f(x, t) dt$$

- Why cannot we write an SDE using time derivatives  $dx/dt$ ,  $dw/dt$ ?
- Hint: recall that the Wiener process has the property:

$$dw(t) \sim \sqrt{dt}$$

so that  $dw/dt$  is proportional to  $1/\sqrt{dt} \rightarrow \infty$ .

**Question 1.** *Is a stochastic process  $x(t)$ , described by an SDE with  $g \neq 0$ , differentiable at any  $t$ ?*

## 2 Solutions to SDE

### Solutions to an SDE

- The existence and uniqueness of solution to an SDE requires some conditions on functions  $f$  and  $g$ .
- If function  $f(x, t)$  is Lipschitz continuous:  $|f(x_1, t) - f(x_2, t)| < A|x_1 - x_2|$
- and if  $g(x, t)$  is bounded and smooth
- then an SDE has unique solution

$$x(t) = x(0) + \int_0^t f(x, s) ds + \int_0^t g(x, s) dw(s)$$

where  $\int_0^t g(x, s) dw(s)$  is a *stochastic* integral (the role of a measure over which we integrate is played by the Wiener process, which, remember, is nowhere differentiable).

## 3 Stochastic integrals

### Riemann vs Stochastic integral

- Let us consider an integral over a differentiable function  $u(t)$ .
- Then the Riemann integral is defined by the limit:

$$\int_0^t g(x, s) du(s) = \lim_{\Delta t \rightarrow 0} \sum_{i=1}^{M-1} g(x(t_i), t_i) \Delta u(t_i)$$

where  $\Delta u(t_i) = u(t_i + \Delta t) - u(t_i)$

- As  $\Delta t \rightarrow 0$ , the difference  $\Delta u(t_i) = u(t_i + \Delta t) - u(t_i)$  tends to the unique limit  $du(t_i) = \dot{u}(t_i) dt$ .
- This does not depend on whether we take *forward* or *backward* differences:

$$\lim_{\Delta t \rightarrow 0} u(t_i + \Delta t) - u(t_i) = \lim_{\Delta t \rightarrow 0} u(t_i) - u(t_i - \Delta t)$$

- This is not the case if, instead of differentiable  $u(t)$ , we integrate over nowhere differentiable  $w(t)$ .

### Difference schemes

We can consider the following difference schemes, each leading to a different result in the limit  $\Delta t \rightarrow 0$ :

- Ito (forward):

$$\Delta_0 x(t) = x(t_{i+1}) - x(t_i)$$

- Backward:

$$\Delta_1 x(t) = x(t_i) - x(t_{i-1})$$

- General (mixture of forward and backward):

$$\Delta_\lambda x(t) = (1 - \lambda)[x(t_{i+1}) - x(t_i)] + \lambda[x(t_i) - x(t_{i-1})]$$

- Stratonovich (or balanced scheme with  $\lambda = 1/2$ ):

$$\Delta_s x(t) = \frac{x(t_{i+1}) - x(t_{i-1}))}{2}$$

### Ito and Stratonovich Integrals

**Definition 2** (General stochastic integral). over stochastic process  $x(t)$  is the limit of the integral sum  $\sum G(x, t) \Delta_\lambda x(t)$  with the general difference scheme  $\Delta_\lambda x(t)$ :

$$I_\lambda[G(x), dx] = \int_0^t G(x, s) d_\lambda x(s)$$

- Ito integral uses the forward scheme ( $\lambda = 0$ ).
- Statonovich integral uses symmetrised scheme ( $\lambda = \frac{1}{2}$ ).
- For  $dx(t) = f(x, t) dt + g(x, t) dw$ , they are related as follows:

$$\int_0^t G(x, s) d_{\frac{1}{2}} x(s) = \int_0^t G(x, s) d_0 x(s) + \frac{1}{2} \int_0^t \frac{\partial G(x, s)}{\partial x} g^2(x, t) dt$$

- Notice what happens if  $dx(t) = f(x, t) dt$  (i.e. if  $g = 0$ ).

### Reading

- Chapter 6, Sec. 6.3, 6.5 (Elliott & Kopp, 2004).

### References

Elliott, R. J., & Kopp, P. E. (2004). *Mathematics of financial markets* (2nd ed.). Springer.