

Theory and Practice of Optimal Mutation Rate Control in Hamming Spaces of DNA Sequences

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August 11, 2011, ECAL

Evolution as an Information Dynamic System

- EPSRC Sandpit '*Math of Life*' (July, 2009):



- Three year project (2010–12)

Middlesex University : Roman Belavkin

University of Warwick : John Aston

University of Keele : Alastair Channon & Elizabeth Aston

University of Manchester : Chris Knight & Rok Krasovec

Introduction

Theory

- Parameter Control Problem

- Relatively Monotonic Landscapes

- Mutation and Adaptation in a Hamming Space

- Analytical Solutions for Special Cases

Practice: Evolving Optimal Mutation Rates

- Inner and Meta GA

- Experimental Results

Conclusions and Questions

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- May depend on changes in the environment (Bjedov et al., 2003).

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- $T := \left(P(x_{s+1} | x_s) \right)$ — Markov operator, $p_s := P(x_s)$

$$p_{s+1} = T p_s = \sum_{x_s} P(x_{s+1} | x_s) P(x_s) \quad \Rightarrow \quad p_{s+t} = T^t p_s$$

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Control

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- $\mu(x)$ — control function, $T_{\mu(x)}, \mathbb{E}_{\mu(x)}\{x_{s+t}\}$.

Optimal Fitness Value Functions

Instantaneous

- Maximum adaptation in no more than λ generations

$$\bar{x}(\lambda) := \sup_{\mu(x)} \{ \mathbb{E}_{\mu(x)} \{ x_{s+t} \} : t \leq \lambda \}$$

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$$\sup_{\mu(x)} \sum_{\lambda=0}^t \mathbb{E}_{\mu(x)} \{ x_{s+\lambda} \} \leq \sum_{\lambda=s}^t \bar{x}(\lambda)$$

Optimal Fitness Value Functions

Information Dynamics (Belavkin, 2010, 2011)

- Maximum adaptation in no more than λ bits between p_s and p_{s+t} :

$$\bar{x}(\lambda) := \sup_{\mu(x)} \{ \mathbb{E}_{\mu(x)} \{ x_{s+t} \} : \mathbb{E} \{ \log(p_{s+t}/p_s) \} \leq \lambda \}$$

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Representation : alphabet $\{1, \dots, \alpha\}$, genotypes $\omega \iff (\alpha_1, \dots, \alpha_l)$.

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Question

Rugged landscape?

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Definition (Relatively Monotonic Landscape)

f is locally monotonic (isomorphic) **relative** to a metric d , if there exist $B(\top, l) := \{\omega : d(\top, \omega) \leq l\}$, $\top = \sup \Omega$, such that $\forall a, b \in B(\top, l)$:

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Example (Needle in a haystack)

$f(\omega) = 1$ if $d(\top, \omega) = 0$; $f(\omega) = 0$ otherwise.

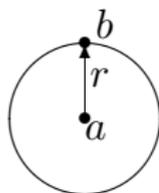
Mutation and Adaptation in a Hamming Space

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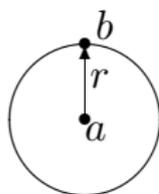


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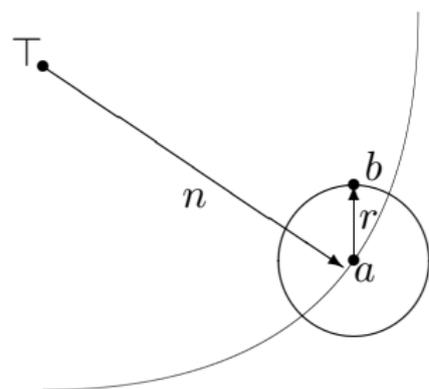


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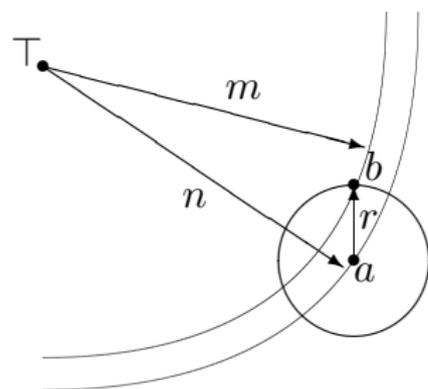
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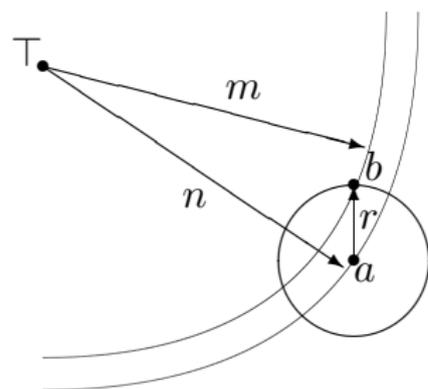
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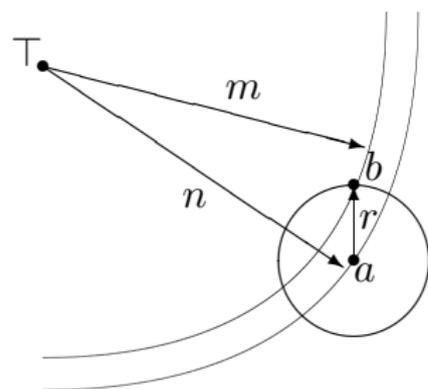


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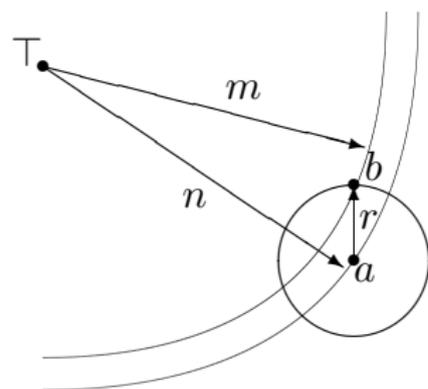
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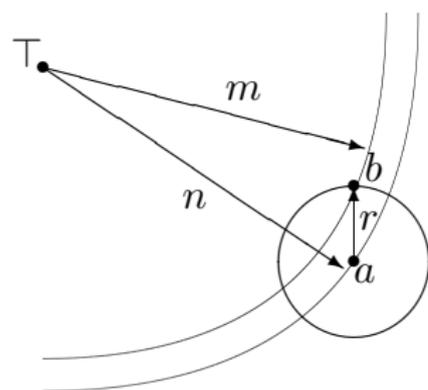
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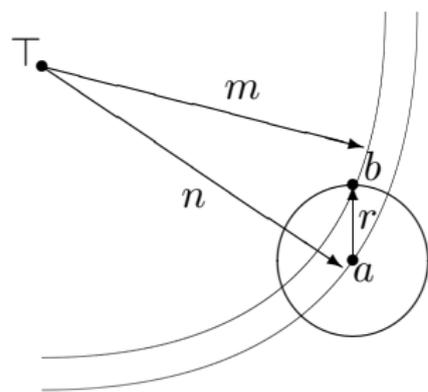


- Expand for all $r \in [0, l]$:

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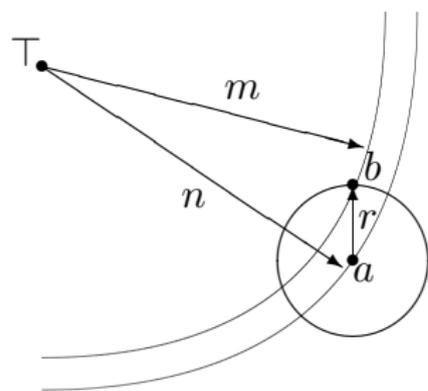
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- In a Hamming space \mathcal{H}_{α}^l :

$$P_{\mu}(r | n) = \binom{l}{r} \mu(n)^r (1 - \mu(n))^{l-r}$$

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- and

$$P(m | n, r) = \frac{|S(\top, m) \cap S(a, r)|_{d(\top, a)=n}}{|S(a, r)|}$$

Adaptation in One Generation

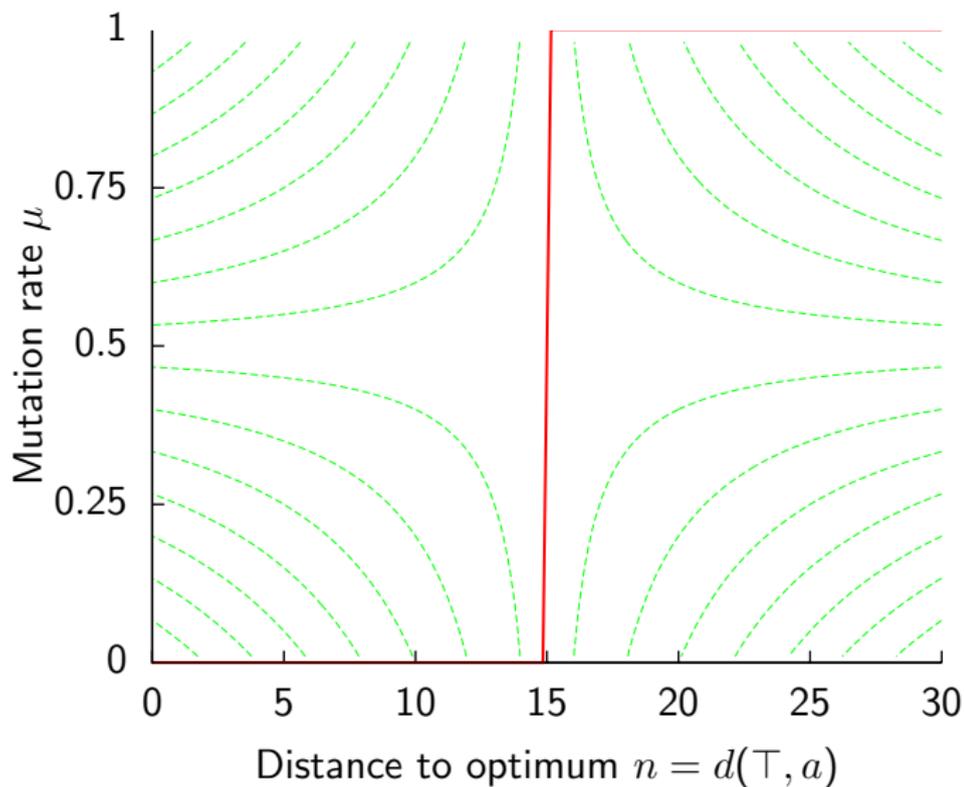
- Minimize $\mathbb{E}\{n_{s+t}\}$ subject to $t \leq 1$.

Adaptation in One Generation

- Minimize $\mathbb{E}\{n_{s+t}\}$ subject to $t \leq 1$.
- In this case the optimal function is

$$\mu(n) := \begin{cases} 0 & \text{if } n < l(1 - 1/\alpha) \\ \frac{1}{2} & \text{if } n = l(1 - 1/\alpha) \\ 1 & \text{otherwise} \end{cases}$$

Step function



Maximizing Probability of Success

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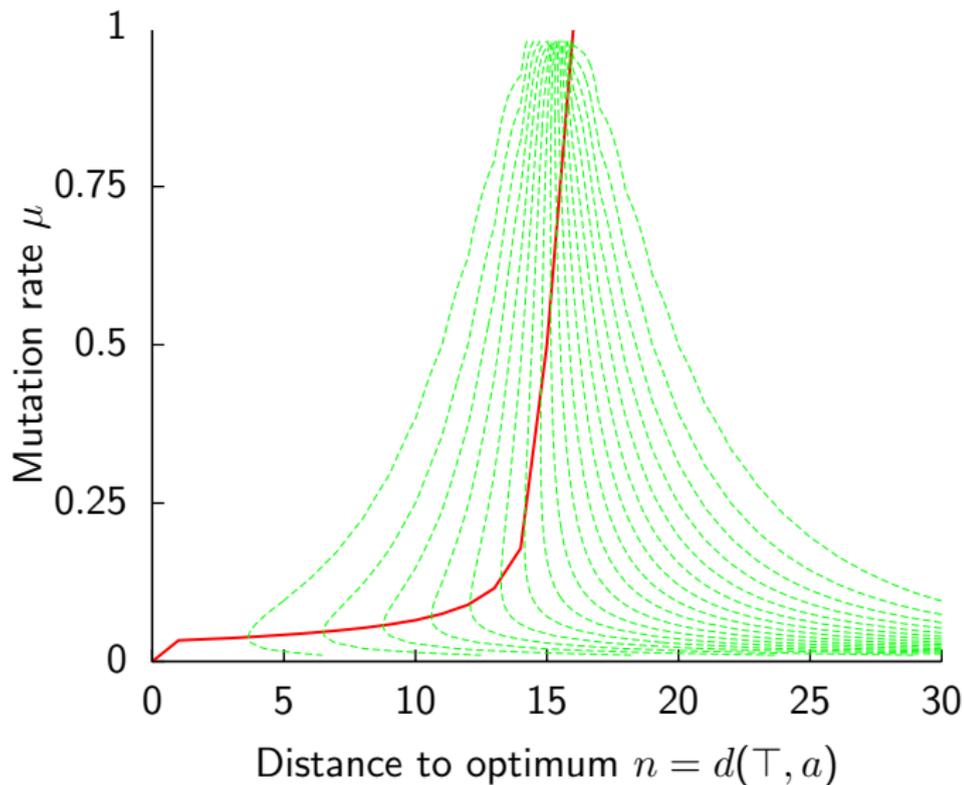
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- This corresponds to maximization of $\mathbb{E}\{u(m, n)\}$, where

$$u(m, n) := \begin{cases} 1 & \text{if } m < n \\ 0 & \text{otherwise} \end{cases}$$

$$\max_{\mu} P_{\mu}(m < n \mid n)$$



Mutation to Optimum

- Probability of mutating directly to optimum

$$P_{\mu}(m = 0 | n) = (\alpha - 1)^{-n} \mu^n (1 - \mu)^{l-n}$$

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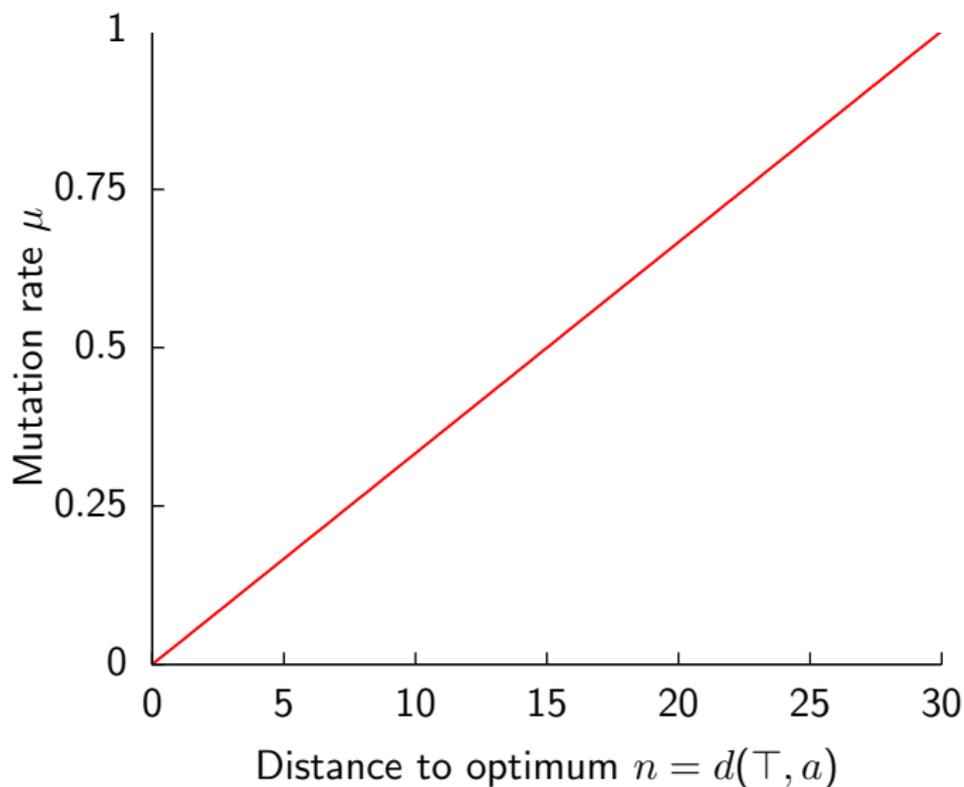
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- Optimal for Boolean landscapes (Needle in a haystack).

Linear function



Information Heuristics $t \leq \lambda \iff I_{KL}(p_{s+t}, p_s) \leq \lambda$

- The optimal μ corresponds to CDF of $P_0(m)$:

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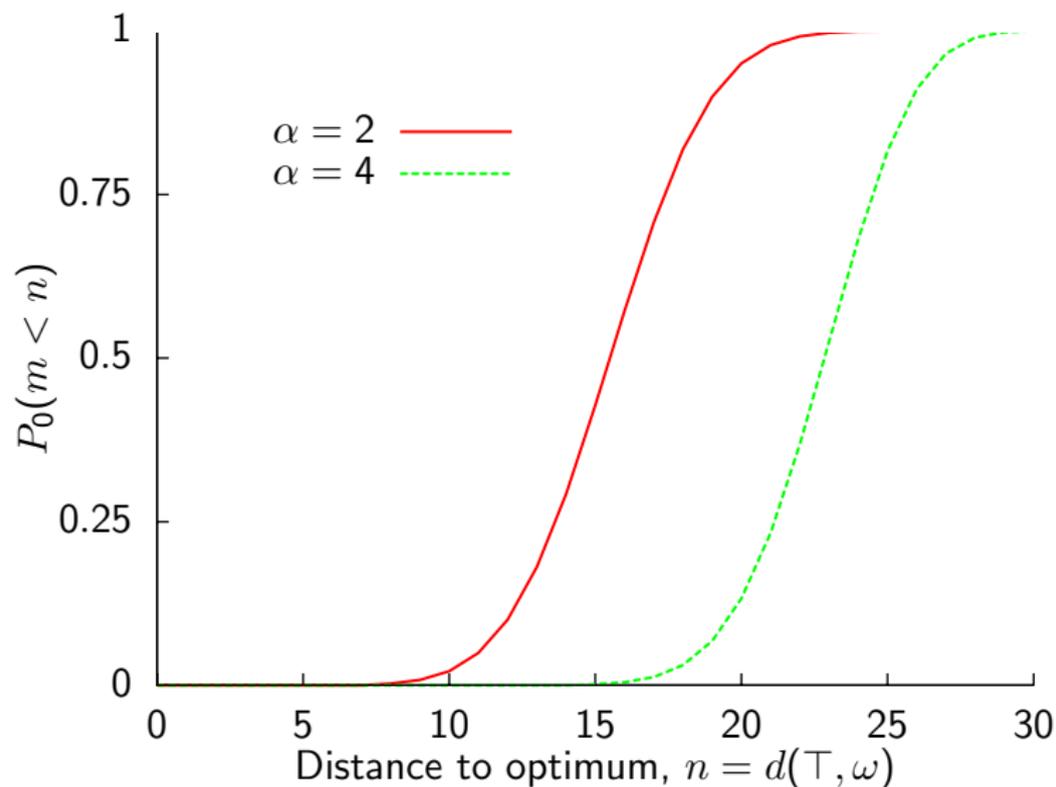
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Informed Mutation Rate

In a (weakly) monotonic landscape we can use CDF of empirical frequency P_e of observed fitness values:

$$P_0(m) \iff P_e(x) \quad \text{and} \quad P_0(m < n) \iff P_e(x_r > x)$$

'Informed' Mutation function



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Practice: Evolving Optimal Mutation Rates

Inner GA

Genotypes : sequences in \mathcal{H}_α^l .

Populations : 100 individuals.

Generations : $t = 500$.

Evolution : mutation only.

Objective : maximize $x = f(\omega)$.

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Inner GA

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Populations : 100 individuals.

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Evolution : mutation only.

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Meta GA

Genotypes : functions $\mu(x)$, $\mu \in [0, 1]$.

Populations : 100 individuals.

Generations : $t = 5 \cdot 10^5$.

Evolution : tournament selection, recombination, mutation.

Objective : maximize $\mathbb{E}\{x\}$ in Inner GA at the last generation.

Experimental Results

- 1 \mathcal{H}_2^{30} (i.e. $\alpha = 2$, $l = 30$) and fitness $f(\omega) = -d(\top, \omega)$, where d is Hamming metric.

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- ② \mathcal{H}_4^{10} (i.e. $\alpha = 4, l = 10$) and fitness $f(\omega) = -d(\top, \omega)$, where d is Hamming metric.

Experimental Results

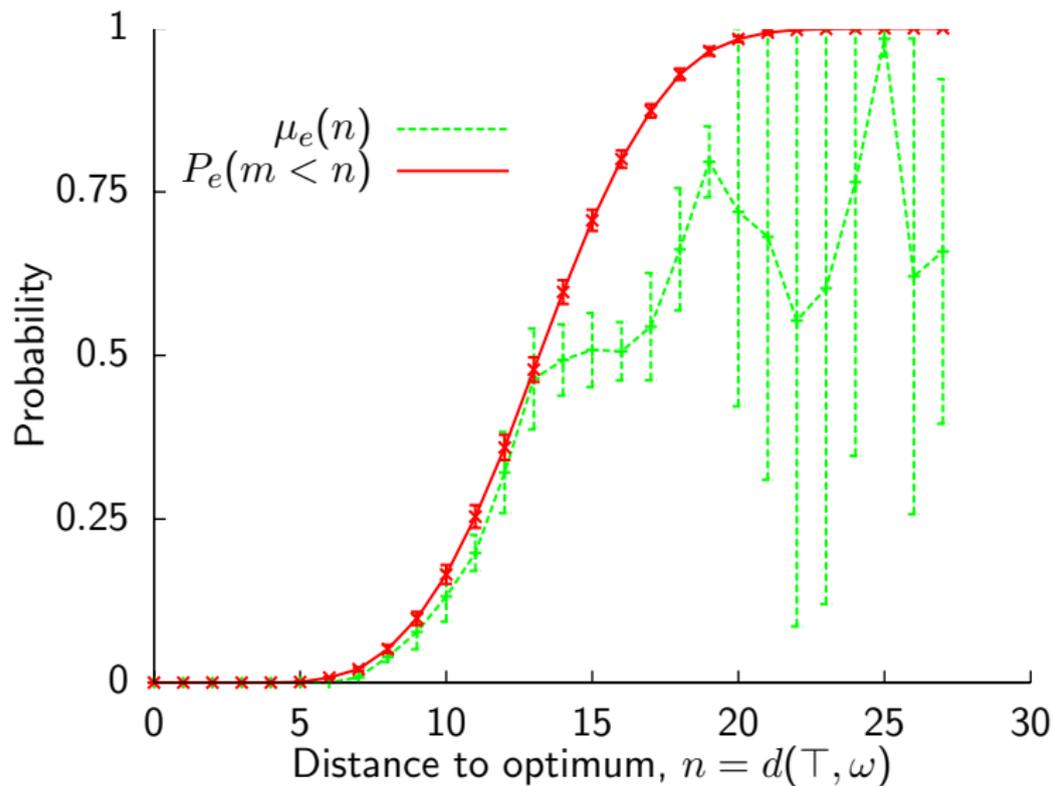
- 1 \mathcal{H}_2^{30} (i.e. $\alpha = 2, l = 30$) and fitness $f(\omega) = -d(\top, \omega)$, where d is Hamming metric.
- 2 \mathcal{H}_4^{10} (i.e. $\alpha = 4, l = 10$) and fitness $f(\omega) = -d(\top, \omega)$, where d is Hamming metric.
- 3 \mathcal{H}_4^{10} (i.e. $\alpha = 4, l = 10$) and fitness $f(\omega)$ defined by a complete DNA-protein affinity landscape for 10-base-pair sequences (Rowe et al., 2010), which we refer to as the aptamer landscape.

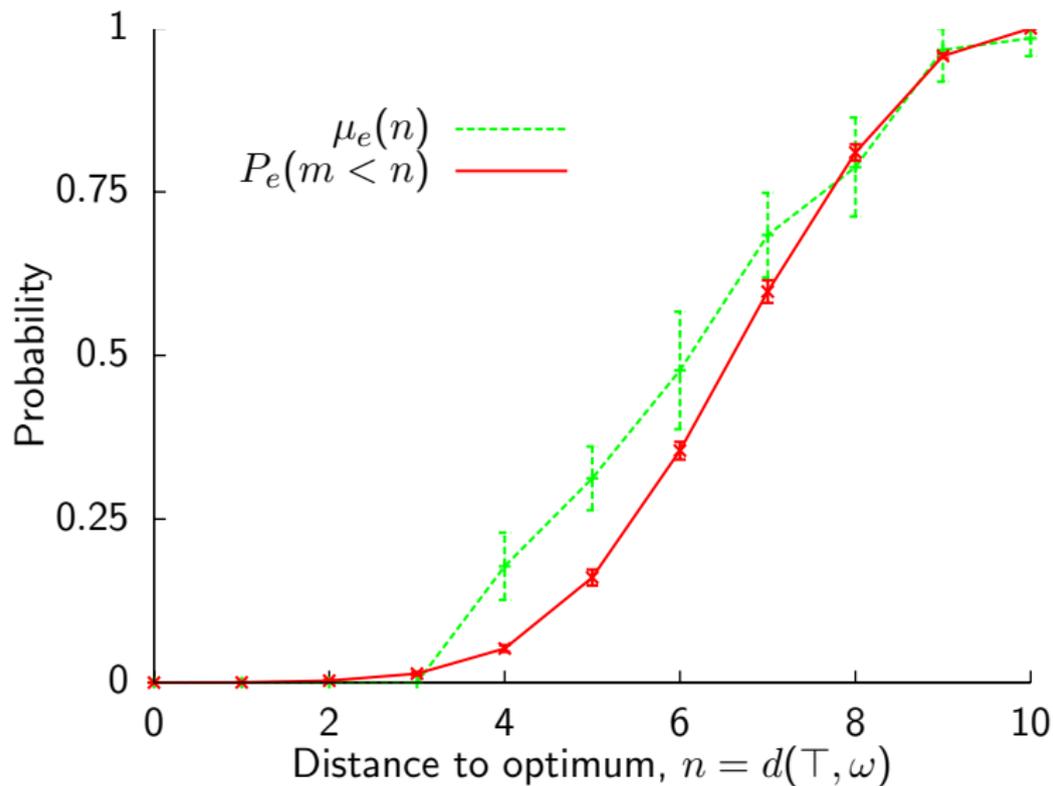
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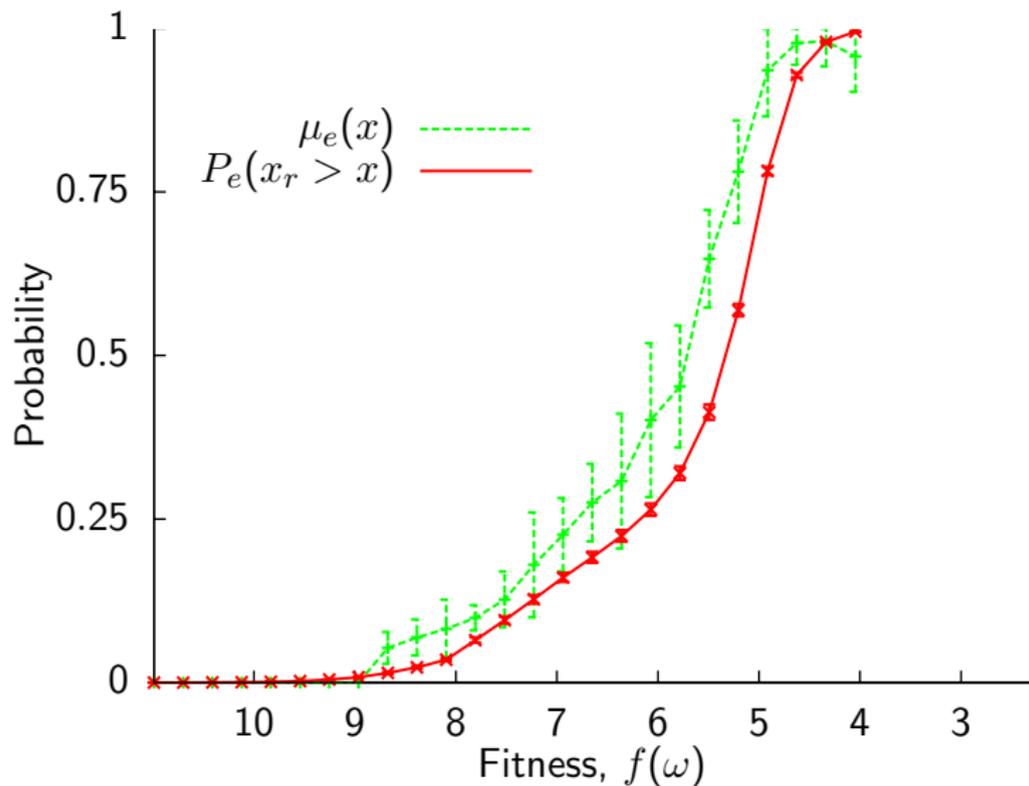
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Output

- $\mu_e(x)$ — evolved mutation rate functions.
- $P_e(x_r > x)$ — CDFs of empirical distributions $P_e(x)$ of fitness.

\mathcal{H}_2^{30} , fitness $f(\omega) = -d(\top, \omega)$


\mathcal{H}_4^{10} , fitness $f(\omega) = -d(\top, \omega)$


\mathcal{H}_4^{10} , fitness the aptamer landscape (Rowe et al., 2010)


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- *Have biological organisms evolved such controls?*

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